



Infinitum

Infinitum Aircore EC Parameters

October 17, 2024



Table of Contents

Section 10: Motor.....	3
Section 11: Operating Limits.....	3
Section 12: Operation Type.....	6
Section 13: Fault Reset.....	8
Section 20: Terminal Settings (AI).....	8
Section 21: Terminal Settings (Digital In).....	10
Section 22: Terminal Settings (Constant Speed).....	11
Section 23: Terminal Settings (Analog Out).....	12
Section 24: Terminal Settings (Digital Out).....	12
Section 30: Monitor (Electrical).....	13
Section 31: Monitor (Environmental).....	13
Section 32: Monitor (Performance).....	15
Section 33: Monitor (Operating).....	16
Section 35: Monitor (Analog In).....	16
Section 36: Monitor (Analog Out).....	16
Section 38: Monitor (Digital Out).....	17
Section 40: Faults.....	17
Section 70: Device Information.....	20
Section 71: Device Information (Lifetime).....	22
Section 86: MAC Address Words.....	22
Section 87: System Controls.....	24
Section 88: Parameter Table "Type" Specifications.....	25

Register Number	Parameter	Description	Options	Type	Read / Write	Units	Default Value	Gen2/3	Gen4	Gen 4.1	Notes
Section 10: Motor											
1001	Run/Stop Command	Operation command to motor	0 = Stop 1 = Start	Bit Field 1	Read / Write	None	None	x	x	x	
1002	Direction Command	Direction command only when motor stopped. Shaft rotation direction viewed from drive end of shaft	0 = CCW 1 = CW	Bit Field 1	Read / Write	None	0=CCW	x	x	x	
1003	Speed Command	Speed command to motor in rpm. Values cannot exceed those in Register # 1101 through 1102	Integer between Speed User Minimum and Speed User Maximum	Unsigned ODP	Read / Write	RPM	100	x	x	x	
Section 11: Operating Limits											
1101	Speed User Minimum	Configurable speed must be greater than Register # 1114	Integer between Model Type Speed Absolute Minimum and Model Type Speed Absolute Maximum	Unsigned ODP	Read / Write	RPM	100	x	x	x	

1102	Speed User Maximum	Configurable speed must be less than Register # 1115	Integer between Model Type Speed Absolute Minimum and Model Type Speed Absolute Maximum	Unsigned ODP	Read / Write	RPM	Motor Rated Speed	x	x	x	
1105	Acceleration Ramp Duration	Duration of ramp time acceleration in seconds. Must be less than Register # 1112	Number between 10 & 90	Unsigned ODP	Read / Write	Seconds	30	x	x	x	
1106	Deceleration Ramp Duration	Duration of ramp time deceleration in seconds. Must be less than Register # 1113	Number between 10 & 90	Unsigned ODP	Read / Write	Seconds	30	x	x	x	
1107 (See notes)	Skip Speed 1	Avoids operating at specified rpm. Bypassed by range defined in Register # 1110	None	Unsigned ODP	Read / Write	RPM	0 = disabled	x	x		Repurposed in Gen4.1
1108 (See notes)	Skip Speed 2	Avoids operating at specified rpm. Bypassed by range defined in Register # 1110	None	Unsigned ODP	Read / Write	RPM	0 = disabled	x	x		Repurposed in Gen4.1
1109 (See notes)	Skip Speed 3	Avoids operating at specified rpm. Bypassed by range defined in Register # 1110	None	Unsigned ODP	Read / Write	RPM	0 = disabled	x	x		Repurposed in Gen4.1

1110 (See notes)	Skip Speed Bandwidth	Specifies bandwidth for speed ranges to be avoided in Register #s 1108 through 1110	0 = 30 RPM, 1 = 60 RPM 2 = 90 RPM	Unsigned ODP	Read / Write	RPM	0 = 30 RPM	x	x		Repurposed in Gen4.1
1107 (See notes)	Skip Speed 1 min	Avoids operating at specified rpm. Minimum value of Skip Speed 1	Number between Motor 100 RPM and User Max RPM	Unsigned ODP	Read / Write	RPM	0 = disabled			x	Repurposed in Gen4.1
1108 (See notes)	Skip Speed 1 max	Avoids operating at specified rpm. Maximum value of Skip Speed 1	Number between Motor 100 RPM and User Max RPM	Unsigned ODP	Read / Write	RPM	0 = disabled			x	Repurposed in Gen4.1
1109 (See notes)	Skip Speed 2 min	Avoids operating at specified rpm. Minimum value of Skip Speed 2	Number between Motor 100 RPM and User Max RPM	Unsigned ODP	Read / Write	RPM	0 = disabled			x	Repurposed in Gen4.1
1110 (See notes)	Skip Speed 2 max	Avoids operating at specified rpm. Maximum value of Skip Speed 2	Number between Motor 100 RPM and User Max RPM	Unsigned ODP	Read / Write	RPM	0 = 30 RPM			x	Repurposed in Gen4.1
1111	Direction Allowed	Fixes rotation of motor to specified direction or enables directional control.	0 = Allow CCW/CW 1 = Fixed CCW 2 = Fixed CW	Enumerated	Read / Write	None	0 = Allow CCW/CW	x	x	x	
1112	Maximum Accel Allowed	Manufacturers maximum acceleration rate allowed in rpm. Configured at factory	None	Unsigned ODP	Read	RPM/Sec	None	x	x	x	

1113	Maximum Deceleration Allowed	Manufacturers maximum deceleration rate allowed in rpm. Configured at factory	None	Unsigned ODP	Read	RPM/Sec	None	x	x	x	
1114	Motor Type Speed Minimum	Motor Type minimum speed for the motor configured at the factory.	None	Unsigned ODP	Read	RPM/Sec	100	x	x	x	
1115	Motor Type Speed Maximum	Motor Type maximum speed for the motor configured at the factory.	None	Unsigned ODP	Read	RPM/Sec	Motor Dependent	x	x	x	
1116	Load Inertia	Inertia modifier to change start actions	Number between 0 and xxxxx	Unsigned ODP	Write		0			x	
Section 12: Operation Type											
1201	Control Mode	Select source for control signals: Register #s 1202 through 1205 must be selected for I/O terminals use Register #s 1202 through 1205 must be overridden to allow Modbus use	0 = I/O Terminals (Analog & Digital) 1 = Modbus Interface (TCP or RTU) 2 = GUI override	Enumerated	Read / Write	None	1 = Modbus Interface (either TCP or RTU)	x	x	x	

1202	Speed Input Source	Selects speed input source input commands. Digital input selection allows desired constant speed settings in Register #s 2201 through 2204	0 = Modbus 1 = Analog 2 = DI1 & DI2 3 = DI2 & DI3 4 = DI3 & DI4	Enumerated	Read / Write	None	0 = Modbus	x	x	x	
1203	Start/Stop Input Source	Selects source for Start and Stop Commands. Digital input selection used in Register # 1202 allows Modbus use.	0 = Modbus 1 = DI1 2 = DI2 3 = DI3 4 = DI4	Enumerated	Read / Write	None	0 = Modbus	x	x	x	
1204	Direction Input Source	Selects source for direction commands. Digital input selection in Register #s 1202 and 1203 allows Modbus use.	0 = Modbus 1 = DI1 2 = DI2 3 = DI3 4 = DI4	Enumerated	Read / Write	None	0 = Modbus	x	x	x	
1205	Clear Fault Input Source	Selects source for fault reset commands. Digital input selection in Register #s 1202 through 1204 allows Modbus use.	0 = Modbus 1 = DI1 2 = DI2 3 = DI3 4 = DI4	Enumerated	Read / Write	None	0 = Modbus	x	x	x	
1210	Speed Override Input Source	Source to use to trigger Override condition		Enumerated	Read / Write	None	0			x	New in 4.1

Section 13: Fault Reset											
1301	Number of Attempts	Defines number of automatic fault reset attempts. Not all faults can be reset automatically If drive exceeds set number it must be reset from source selected in Register # 1205	0 = Stop on fault 1 through 10 = number of restart attempts per fault 99 = Keep trying to restart	Unsigned 0DP	Read / Write	None	3 = 3 attempts	x	x	x	
1302	Reset Delay	Defines time between successive automatic reset attempts	0.0 = Immediately reset decimal between 0.0-120.0 = Time in seconds, 0.5 second increments	Unsigned 1DP	Read / Write	Seconds	10 = 5 seconds	x	x	x	
Section 20: Terminal Settings (AI)											
2001	AI1 Function	Select function for Analog Input AI1.	0 = Speed control	Enumerated	Read / Write	None	0 =Speed Control	x	x	x	
2002	AI1 Minimum Setting	Defines minimum percent value corresponding to minimum mA(V) signal for analog input AI1: 0 = 0 to 100% (0 to	Enter number between 0 & 100 Must be less than Register # 2003	Unsigned 1DP	Read / Write	%	speed user minimum (100 rpm) / speed user minimum(x	x	x	

		20 mA) 20 = 20 to 100% (4 to 20 mA)					Motor Rated Speed) * 100 %				
2003	AI1 Maximum Setting	Defines minimum percent value corresponding to maximum mA(V) signal for analog input AI1: 80 = 0 to 80% (0 to 16 mA) 100 = 0 to 100% (0 to 20 mA)	Enter number between 0 & 100 Must be greater than Register # 2002	Unsigned 1DP	Read / Write	%	100 = 100%	x	x	x	
2006	AI1 Type Selection	Selects input type for AI1	0 = Voltage 1= Current	Enumerated	Read / Write	None	0 = Voltage	x	x	x	
2010	AI1 Open Max	Upper bound for Analog failover voltage	0 to 100%	Unsigned 0DP	Read / Write	%	0			x	New in 4.1
2011	AI1 Open Speed	Analog Failover speed	100 to User Max RPM	Unsigned 0DP	Read / Write	RPM	0			x	New in 4.1
2012	AI1 Stop/Override Min	Lower range setting for Analog stop voltage	0 to 100%	Unsigned 0DP	Read / Write	%	0			x	New in 4.1

2013	AI1 Stop/Override Max	Upper range setting for Analog stop voltage	0 to 100%	Unsigned ODP	Read / Write	%	0			x	New in 4.1
Section 21: Terminal Settings (Digital In)											
2101	DI1 Function	Indicates behavior assigned to DI1 respective to input parameters for Register #s 1202 through 1205.	0 = None 1 = Run 2 = Direction 3 = Clear Fault 4 = Constant Speed	Enumerated	Read	None	None	x	x	x	
2102	DI2 Function	Indicates behavior assigned to DI1 respective to input parameters for Register #s 1202 through 1205.	0 = None 1 = Run 2 = Direction 3 = Clear Fault 4 = Constant Speed	Enumerated	Read	None	None	x	x	x	
2103	DI3 Function	Indicates behavior assigned to DI1 respective to input parameters for Register #s 1202 through 1205.	0 = None 1 = Run 2 = Direction 3 = Clear Fault 4 = Constant Speed	Enumerated	Read	None	None	x	x	x	
2104	DI4 Function	Indicates behavior assigned to DI1 respective to input parameters for Register #s 1202 through 1205.	0 = None 1 = Run 2 = Direction 3 = Clear Fault 4 = Constant Speed	Enumerated	Read	None	None	x	x	x	

Section 22: Terminal Settings (Constant Speed)											
2201	Constant Speed 1	Speed motor operates when corresponding combination of digital inputs are activated. Speed must within parameters for Register #s 1101 through 1102	Number between Speed User Minimum and Speed User Maximum	Unsigned ODP	Read / Write	RPM	100	x	x	x	
2202	Constant Speed 2	Speed motor operates when corresponding combination of digital inputs are activated. Speed must within parameters for Register #s 1101 through 1102	Number between Speed User Minimum and Speed User Maximum	Unsigned ODP	Read / Write	RPM	100	x	x	x	
2203	Constant Speed 3	Speed motor operates when corresponding combination of digital inputs are activated. Speed must within parameters for Register #s 1101 through 1102	Number between Speed User Minimum and Speed User Maximum	Unsigned ODP	Read / Write	RPM	100	x	x	x	

2204	Constant Speed 4	Speed motor operates when corresponding combination of digital inputs are activated. Speed must within parameters for Register #s 1101 through 1102	Number between Speed User Minimum and Speed User Maximum	Unsigned 0DP	Read / Write	RPM	100	x	x	x	
2205	Override Speed	Speed to use in Override condition	Number between Speed User Minimum and Speed User Maximum	Unsigned 0DP	Read / Write	RPM	0			x	New in 4.1
Section 23: Terminal Settings (Analog Out)											
2301	AO1 Function	Connects motor signal to analog output AO1	0 = Speed 1 = Torque 2 = Power 3 = Current 4 = 10 V (for potentiometer)	Enumerated	Read / Write	None	0 = Speed	x	x	x	Only uses Speed and 10V
2305	AO1 Type	Selects output signal type	0 = Voltage 1 = Current	Bit Field 1	None	None	0 = Voltage	x	x	x	
Section 24: Terminal Settings (Digital Out)											
2401	DO1 Function	Selects motor status indicated by	0 = None 1 = Active	Enumerated	Read /	None	1 = Active	x	x	x	

		corresponding output	2 = Fault 3 = At Range		Write						
2402	DO2 Function	Selects motor status indicated by corresponding output	0 = None 1 = Active 2 = Fault 3 = At Range	Enumerated	Read / Write	None	2 = Fault	x	x	x	
Section 30: Monitor (Electrical)											
3001	DC Bus Voltage	Indication of DC Bus Voltage (V)	None	Signed 1DP	Read	Volts (V)	None	x			Removed for Gen4
3004	Average RMS Current	Indication of Average RMS motor phase current (A)	None	Signed 2DP	Read	Amps (A)	None	x			Removed for Gen4
Section 31: Monitor (Environmental)											
3101	Stator RTD	Displays temperature value from associated sensor. Defined in Register # 3151	None	Signed 0DP	Read	°C	None	x			Gen2 uses stator RTD
3102	Stator Average	Displays temperature value from associated sensor. Defined in Register # 3152	None	Signed 0DP	Read	°C	None		x	x	Gen4 uses average of two thermistors
3103	T3 Heatsink	Displays temperature value	None	Signed 0DP	Read	°C	None		x	x	

		from associated sensor. Defined in Register # 3153									
3104	T2 Stator NTC1	Displays temperature value from associated sensor. Defined in Register # 3154	None	Signed 0DP	Read	°C	None		x	x	
3105	Inv board temp	Displays temperature value from associated sensor. Defined in Register # 3155	None	Signed 0DP	Read	°C	None	x	x	x	
3106	T3 Heatsink	Displays temperature value from associated sensor. Defined in Register # 3156	None	Signed 0DP	Read	°C	None	x			
3107	T4 Stator NTC2	Displays temperature value from associated sensor. Defined in Register # 3157	None	Signed 0DP	Read	°C	None		x		
3114	T14 CIM Board Temp	Displays temperature value from associated sensor. Defined in Register # 3164	None	Signed 0DP	Read	°C	None	x	x	x	
3151	Temp Label 1	Factory set label value measured in Register # 3101	None	Enumerated	Read	None	Stator Calc Temp	x			Gen2 uses stator RTD temp sensor

3152	Temp Label 2	Factory set label value measured in Register # 3102	None	Enumerated	Read	None	Stator Calc Temp		x	x	Average of two thermistors
3153	Temp Label 3	Factory set label value measured in Register # 3103	None	Enumerated	Read	None	Heat Sink Temp		x	x	Gen4 and later only
3154	Temp Label 4	Factory set label value measured in Register # 3104	None	Enumerated	Read	None	Stator Thermistor 1 Temp		x	x	Gen4 and later only
3155	Temp Label 5	Factory set label value measured in Register # 3105	None	Enumerated	Read	None	Inverter Board Temp	x			
3156	Temp Label 6	Factory set label value measured in Register # 3106	None	Enumerated	Read	None		x			Gen2 only
3157	Temp Label 7	Factory set label value measured in Register # 3107	None	Enumerated	Read	None	Stator Thermistor 2 Temp		x	x	Gen4 and later only
3164	Temp Label 14	Factory set label value measured in Register # 3114	None	Enumerated	Read	None	CIM Board Temp	x	x	x	
Section 32: Monitor (Performance)											
3201	Output Torque	Indication of output torque calculated by drive	None	Signed 3DP	Read	Nm	None	x			Removed for Gen4

3202	Output Power	Indication of output power calculated by drive	None	Unassigned 0DP	Read	Watts (W)	None	x			Removed in Gen4
Section 33: Monitor (Operating)											
3301	Run/Stop Actual	Displays motor Run/Stop status	None	Bit Field 1	Read	Running or Stopped	None	x	x	x	
3302	Direction Actual	Displays direction of motor rotation	None	Bit Field 1	Read	CW or CCW	None	x	x	x	
3303	Speed Actual	Displays measured speed of motor	None	Signed 0DP	Read	RPM	None	x	x	x	
Section 35: Monitor (Analog In)											
3501	AIN1 Value	Displays input signal to AI1	None	Unsigned 1DP	Read	%	None	x	x	x	
Section 36: Monitor (Analog Out)											
3601	AOUT1 Value	Displays signal out to AO1	None	Unsigned 1DP	Read	%	None	x	x	x	
Section 37: Monitor (DI)											
3701	DIN1 Value	Displays status of DI1	None	Bit Field 1	Read	None	None	x	x	x	

3702	DIN2 Value	Displays status of DI2	None	Bit Field 1	Read	None	None	x	x	x	
3703	DIN3 Value	Displays status of DI3	None	Bit Field 1	Read	None	None	x	x	x	
3704	DIN4 Value	Displays status of DI4	None	Bit Field 1	Read	None	None	x	x	x	
Section 38: Monitor (Digital Out)											
3801	DOUT1 Value	Displays status of DO1	None	Bit Field 1	Read	None	None	x	x	x	
3802	DOUT2 Value	Displays status of DO2	None	Bit Field 1	Read	None	None	x	x	x	
Section 40: Faults											
4001	Active Faults	Monitors for active Faults	None	Bit Field 1	Read	None	None	x	x	x	
4003	Clear Faults	Write "1" to this register to clear Faults	None	Unsigned 0DP	Write	None	None	x	x	x	
4011	Fault Word	Displays encoded Fault word	None	Bit Fault 0 FAULT_HW 1 FAULT_Overcurrent 2 FAULT_Overvoltage	Read	None	None	x	x	x	

				3 FAULT_Undervoltag e 4 FAULT_Overtemp 5 FAULT_GateDriver 6 FAULT_GateDriver UV 7 Reserved 8 FAULT_UARTCom mError 9 Reserved 10 Reserved 11 FAULT_MotorPara meters 12 FAULT_Motor_Disa ble 13 Fault_Inverter_Flas h 14 Fault_Inverter_Erro r 15 Fault_CIM							
4012	Gate Drive Fault	Fault Word – Gate Drive	None	Bit Gate Fault 0 GATE_DRV_FLT 1 GATE_DRV_FLT_ Undefined	Read	None	None	x	x	x	

				2 GATE_DRV_FLT_undefined 3 GATE_DRV_FLT_UVLO							
4013	Over Temp Fault	Fault Word- Over Temp	None	bit OverTemp Src 0 OVRTMP_Therm1 (1) 1 OVRTMP_Therm2 (2) 2 OVRTMP_Therm3 (4) 3 OVRTMP_Therm4 (8) 3 OVRTMP_StatorRTD (64) 4 Reserved (128) 5 OVRTMP_Board (256)	Read	None	None	x	x	x	
4014	CIM Fault Status	Fault Word – Comm/IO	None	bit CIM Fault 0 CIM_FAULT_INVCOMM 1 CIM_FAULT_DIN 2 CIM_FAULT_AIN	Read	None	None	x	x	x	

				3 CIM_FAULT_USER 24V 4 CIM_FAULT_INVS ETT							
Section 70: Device Information											
7002	Motor Max Current	Displays maximum motor current	None	Unsigned 2DP	Read	Amps (A)	None	x	x	x	
7003	Motor Voltage	Displays nominal VAC for motor	None	Unsigned 0DP	Read	Volts (V)	None	x	x	x	
7004	Motor Serial No (Word 1)	Displays Word 1 of motor serial number	None	Unsigned 0DP	Read	None	None		x	x	
7005	Motor Serial No (Word 2)	Displays Word 2 of motor serial number	None	Unsigned 0DP	Read	None	None		x	x	
7006	Motor Serial No (Word 3)	Displays Word 3 of motor serial number	None	Unsigned 0DP	Read	None	None		x	x	
7007	Motor Serial No (Word 4)	Displays Word 4 of motor serial number	None	Unsigned 0DP	Read	None	None		x	x	
7008	Motor Serial No (Word 5)	Displays Word 5 of motor serial number	None	Unsigned 0DP	Read	None	None		x	x	
7009	Motor Serial No (Word 6)	Displays Word 6 of motor serial number	None	Unsigned 0DP	Read	None	None		x	x	
7010	Motor Serial No (Word 7)	Displays Word 7 of motor serial number	None	Unsigned 0DP	Read	None	None		x	x	

7011	Old SN1	Displays Word 1 of motor serial number	None	Unsigned ODP	Read	None	None	x			
7012	Old SN2	Displays Word 2 of motor serial number	None	Unsigned ODP	Read	None	None	x			
7013	Old SN3	Displays Word 3 of motor serial number	None	Unsigned ODP	Read	None	None	x			
7014	Old SN4	Displays Word 4 of motor serial number	None	Unsigned ODP	Read	None	None	x			
7021	Motor Model	Displays Motor Model number	None	Unsigned ODP	Read	None	None	x	x	x	
7031	Inverter Firmware Major	Displays Inverter Firmware Major Version	None	Unsigned ODP	Read	None	None	x	x	x	
7032	Inverter Firmware Minor	Displays Inverter Firmware Minor Version	None	Unsigned ODP	Read	None	None	x	x	x	
7033	CIM Firmware Major	Displays CIM Major Version	None	Unsigned ODP	Read	None	None	x	x	x	
7034	CIM Firmware Minor	Displays CIM Minor Version	None	Unsigned ODP	Read	None	None	x	x	x	
7035	Motor Type	Displays Motor Type	None	Unsigned ODP	Read	None	None	x	x	x	
7036	Hardware ID	Displays HW ID	None	Unsigned ODP	Read	None	None	x	x	x	
7039	Hardware ID INV	Displays Inv ID	None	Unsigned ODP	Read	None	None		x	x	Added for Gen4

7040	Hardware ID VFD	Displays VFD ID	None	Unsigned 0DP	Read	None	None		x	x	Added for Gen4
7041	Hardware ID CIM	Displays CIM	None	Unsigned 0DP	Read	None	None		x	x	Added for Gen4
7042	Horsepower	Displays Horsepower	None	Unsigned 0DP	Read	None	None		x	x	Added for Gen4
7043	Frame Size	Displays Fame Size	None	Unsigned 0DP	Read	None	None		x	x	Added for Gen4
7044	Stator Type	Stator Type	None	Unsigned 0DP	Read	None	None		x	x	Added for Gen4
Section 71: Device Information (Lifetime)											
7101	Drive Runtime	Displays Drive Runtime hours	0 = Reset	Unsigned 0DP	Read / Write	Hour (hr)	None	x	x	x	
7102	Motor Runtime	Displays Motor Runtime hours	0 = Reset	Unsigned 0DP	Read / Write	Hour (hr)	None	x	x	x	
7103	Motor MWh	Displays power consumed by motor (MWh)	0 = Reset	Unsigned 1DP	Read / Write	Mega Watt Hour (MWh)	None	x			Removed for Gen4
Section 86: MAC Address Words											
8601	RTU Slave Address	Modbus RTU slave address	1-247	Unsigned 0DP	Read / Write	None	247	x	x	x	

8602	RTU Baud Rate	Modbus RTU baud rate	0 = 1200 bps 1 = 2400 bps 2 = 4800 bps 3 = 9600 bps 4 = 19200 bps 5 = 38400 bps 6 = 57600 bps 7 = 76800 bps 8 = 115200 bps	Enumerated	Read / Write	None	4 = 19200 bps	x	x	x	
8603	RTU Parity	Modbus RTU parity	0 = No Parity 1 = Even Parity 2 = Odd Parity	Enumerated	Read / Write	None	1 = Even Parity	x	x	x	
8604	MAC Address (Word 1)	MAC Address bytes 1 & 2	None	Unsigned ODP	Read	None	None	x	x	x	
8605	MAC Address (Word 2)	MAC Address bytes 3 & 4	None	Unsigned ODP	Read	None	None	x	x	x	
8606	MAC Address (Word 3)	MAC Address bytes 5 & 6	None	Unsigned ODP	Read	None	None	x	x	x	
8607	IoT Update Rate	IoT Update Frequency in seconds (default is 60)	0-65535 = 0-65535 seconds	Unsigned ODP	Read / Write	Seconds	900 = 900 Seconds	x			
8611	Modbus Monitor Enable	Enable for Modbus Monitor failover feature	0 = Disable 1 = Enable	Bit Field 1	Read /	None	0 = Disable	x	x	x	

8612	Modbus Monitor Timeout	Time in seconds to detect Modbus communications fault	0-65535 = 0-65535 seconds	Unsigned ODP	Write	Seconds	30 = 30 Seconds	x	x	x	
8613	Modbus Monitor Resume	If set, resume previous speed when communications resumes	0 = Disable 1 = Enable	Bit Field 1	Read /	None	0 = Disable	x	x	x	
8614	Modbus Monitor Stop	Stop motor in event of loss of communications	0 = Fail Over Speed 1 = Stop Motor	Bit Field 1	Write	None	0 = Fail Over Speed	x	x	x	
8615	Modbus Monitor Speed	Interim motor speed during loss of communications	Integer between Speed User Minimum and Speed User Maximum	Unsigned ODP	Read /	RPM	100 RPM	x	x	x	
Section 87: System Controls											
8701	Parameter Save	Saves valid parameter values to permanent memory	None	Bit Field 1	Read / Write	None	None	x	x	x	

Section 88: Parameter Table “Type” Specifications

Type	Description	Words	Minimum Value	Maximum Value
Signed 0DP	Signed 16-bit number with no characters past decimal point	1	-32768	32767
Signed 1DP	Signed 16-bit number with one character past decimal point	1	-3276.8	3276.7
Signed 2DP	Signed 16-bit number with two characters past decimal point	1	-327.68	327.67
Signed 3DP	Signed 16-bit number with three characters past decimal point	1	-32.768	32.768
Unsigned 0DP	Unsigned 16-bit number with no characters past decimal point	1	0	65536
Unsigned 1DP	Unsigned 16-bit number with one character past decimal point	1	0.0	6553.6
Unsigned 2DP	Unsigned 16-bit number with two characters past decimal point	1	0.00	655.36
Enumerated	An unsigned number defined by an enumerated list. The list is defined in a corresponding table	1	0	65536